

Disc brakes with the electrohydraulic thrusters of ZE type are adjusted to the cooperation with brake discs on their lateral surface. Braking torque is created by the spring inbuilt in the body of the thruster or by the lever system (series 100), which through the compound lever causes pressing down of the brake shoes with friction linings to the friction surface of the brake disc.

Turning on the supply voltage of the thruster starts the motor and the pump forcing the oil under the piston of the thruster which causes that the piston moves up and the brake is released. Turning off the supply causes that the piston moves down (under the influence of the spring inbuilt in the thruster or outside the thruster- series 100) and the brake is applied. The speed of raising or falling of the piston can be adjusted through the use of the valve delaying the falling or lifting of the piston.

ZE thrusters can be equipped with inductive sensor of piston rod position mounted outside or with external mechanical switch signaling upper or lower position of the piston rod. Above mentioned sensors and switches require appropriate source of supply.

#### VARIANTS:

- **ATZ** – standard
- **ATZ (series 100)** – with outer spring
- **ATG** – mining
- **ATG (series 100)** – mining with outer spring

#### ELECTROHYDRAULIC THRUSTORS

Version N/1 – for outdoor use in a temperate climate. The thruster has an oil-tight housing with a junction box with IP 65 rating according to PN-EN 60529:2003. The thruster in the standard version is designed for operation in the vertical position and a position deviated from vertical by a 30° angle.

**Conditions of operation:** ambient temperature: –25°C to +40°C (electroinsulating transformer oil); –40°C to +50°C (silicone oil).

#### VERSIONS

- **ZE...** thruster without brake spring [Type of operation S1, S3 do 100% 2000 c/h]
- **ZE...S...** thruster with the brake spring, [operating mode S1, S3 to 100% 2000 c/h]

#### WORKING CONDITIONS:

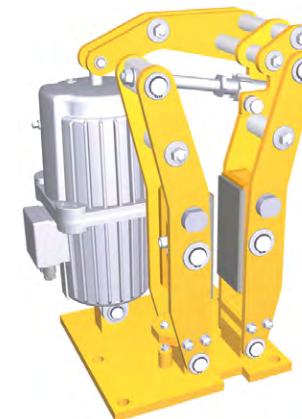
The brakes are intended for operation in moderate climate on the land. In the case of operation “in the open air” it is recommended to shield the brake to protect it against the precipitation. The brakes are intended mainly for operation in horizontal position (the basis mounted on the horizontal surface). Operation in other position is possible only after consultation with the manufacturer.

**APPLICATIONS:** belt conveyors, fans, drives of cranes, devices of continuous transport, machines for iron and steel, building, paper-making and other industries.

**MATERIAL:** construction of the brake – steel; brake shoes – spheroidal iron cast; asbestos-free friction lining; ZE thruster body – aluminium, ExZE – iron cast; bolts made of stainless steel, self-lubricating sleeves.

#### OPERATION IN THE AREAS WITH THE DANGER OF EXPLOSIONS:

Mining brakes are intended for the operation in the areas with the danger of explosion in the conditions specified for group: I M2, II 2D, II 2G.



- **ZEW...(S)...** thruster with the brake spring and connector (allows to signal the upper piston rod position) [operating mode S1, S3 do 100% 2000 c/h]
- **ZEM...(S)...** thruster with the brake spring and electromagnet (maintains the piston in its upper position without necessity of supplying the thruster motor) [type of work S1, S3 40% 600 c/h] 38 V DC electromagnet supply voltage, current intensity of 0,4–0,45 A for size thruster smaller than ZEM 2500 and 38V DC and 0,8 A for size ZEM 2500... and ZEM 3200
- **ZE...(S)...Cm** thruster equipped with an external mechanical switch (PDM1F12PZ11) with a NO/NC contact system. This switch, depending on the position of the measuring slide, can indicate whether the piston rod is in the upper or lower position. After consultation, indication of a different piston rod position is also possible.

### Technical details of the mechanical switch:

AC-15 and DC-13 utilisation categories  
 Rated operational voltage: AC:24/120/240V 50/60Hz  
 DC: 24/125/250 V  
 Rated operational currents: AC:10/6,3/1,8 A, DC: 2,8/0,55/0,27 A  
 Contact system: NO/NC  
 IP 66 rating

- **ZE...(S)...Ci...** A thruster equipped with an inductive sensor located on the outside. This sensor can indicate the position of the piston rod over its entire extension range. The position of the piston rod can be determined at any point using a sliding measuring head.

### Technical details of the inductive sensor:

Supply voltage: from 12 to 24 VDC  
 Current: 10 mA max  
 IP 67 rating

Marking	Sensor type	Operation method	Output type
B1	E2A-M18-KS08-M1-B1	NO	PNP
C1	E2A-M18-KS08-M1-C1	NO	NPN
B2	E2A-M18-KS08-M1-B2	NC	PNP
C2	E2A-M18-KS08-M1-C2	NC	NPN

Versions with delay valves:

- ZE.. P.....** – with a lifting delay valve
- ZE.. O.....** – with a falling delay valve
- ZE.. T.....** – with a lifting and falling delay valve

(S1 – Operation continuous, S3 – Operation discontinuous)

For the supply of brakes with ZEM thruster, a suitable UZ power supply system supplied with alternating current, which allows an electromagnet to be connected to it, may be provided

### EXPLOSION-PROOF ELECTROHYDRAULIC THRUSTOR

The thruster is made as an explosion-proof device in a flameproof casing with intrinsically safe signalling circuits and a connection box with IP 65 rating according to PN-EN 60529:2003.

The thruster in the standard version is designed for operation in the vertical position and a position deviated from vertical by a 30° angle.

The thruster is equipped with a limit switch which can be used to indicate the movement of the piston rod to its upper extreme position.

**Ambient temperature:** from -20°C to +40°C.

### VERSIONS

- **ExZE...S...** thruster with the brake spring [Type of operation S1,S3 to 100% 2000c/h]
- **ExZEM...S...** thruster with the brake spring and electromagnet (maintains the piston in upper position without necessity of supplying the thruster motor – supply voltage of the electromagnet 42 VAC) \* Type of operation S1, S3 to 40% 600 c/h]

The thrusters are intended for the operation in the areas with the danger of explosion in the conditions specified for group I M2, II 2D, II 2G.

The thrusters can be manufactured with the connector with "r" (NC) opening contact or "z" (NO) closing contact and thermal protection in the form of bimetallic switch "1" or posistor sensor "2".

**METHOD OF MARKING:**

[ name ] - [ D<sub>H</sub> ] / [ B ] - [ version ] - [ mounting ] - [ thrustor marking ] - [ size ] [ type ] - [ version\* ]

\* only when it concerns a given type, where:

<b>name</b>	e.g. disc brake	<b>thrustor marking</b>	<i>see below</i>
<b>D<sub>H</sub></b>	diameter of the disc brake [mm]	<b>size</b>	e.g. 001
<b>B</b>	brake disc thickness [mm]	<b>type</b>	e.g. ATZ
<b>version</b>	left "L", right "R"	<b>version</b>	WS... – special (individual arrangements)
<b>mounting of the thrustor junction box</b>	position "A", position "B"		

**METHOD OF THRUSTOR MARKING:**

**TYPE ZE**

[ version ] - [ delay valve\* ] - [ size ] / [ stroke ] [ spring\* ] · [ oil\* ] · [ voltage ] [ sensor\* ]

\* only when it applies, where:

<b>version</b>	ZE – basic ZEW – with connector ZEM – with electromagnet	<b>thrustor size</b>	e.g. 1250
<b>delay valve</b>	without the valve – omit the marking P – lifting O – falling T – lifting and falling	<b>thrustor stroke</b>	e.g. 50
		<b>spring</b>	e.g. S 450
		<b>oil</b>	normally transformer oil (omit the marking)
		<b>voltage</b>	e.g. 500 V AC/50 Hz
		<b>sensor marking</b> (if required)	– e.g. inductive B1 – "Ci-B1", mechanical "Cm"

**TYPE ExZE**

[ version ] - [ size ] / [ stroke ] [ contact ] [ protection ] [ spring\* ] · [ voltage ]

\* only when it applies, where:

<b>version</b>	ExZE – basic ExZEM – with electromagnet	<b>contact</b>	"r" – opening, "z" – closing
<b>thrustor size</b>	e.g. 1250	<b>protection</b>	bimetallic switch "1", posistor sensor "2"
<b>thrustor stroke</b>	e.g. 60	<b>spring</b>	e.g. S 450
		<b>voltage</b>	e.g. 500 V AC/50 Hz